

Unipolar Detection Hall IC

(N Pole Polarity Detection)

BU52069GWZ

General Description

The BU52069GWZ is unipolar Hall IC detects only N pole.

This Hall IC product can be in tablets, smart phones, and other applications in order to detect open and close of the cover.

Features

- Unipolar Detection (N pole)
- Micro Power Operation (Small Current Using Intermittent Operation Method)
- Ultra-compact CSP4 Package (UCSP35L1)

Applications

 Tablets, Smart Phones, Notebook Computers, Digital Video Cameras, Digital Still Cameras, etc.

Key Specifications

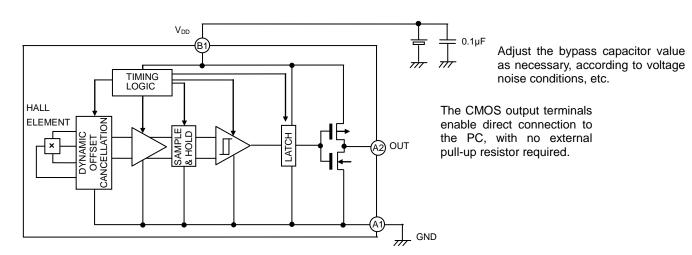
V_{DD} Voltage Range: 1.65V to 3.6V
 Operate Point: -43.3mT(Typ)
 Hysteresis: 1.6mT(Typ)
 Period: 50ms(Typ)
 Supply Current (AVG): 3.5µA (Typ)
 Output Type: CMOS
 Operating Temperature Range: -40°C to +85°C

Package UCSP35L1

W(Typ) x D(Typ) x H(Max) 0.80mm x 0.80mm x 0.40mm



Typical Application Circuit, Block Diagram, Pin Configurations and Pin Descriptions



Pin No.	Pin Name	Function		
A1	GND	Ground		
A2	OUT	Output (React to the north pole)		
B1	V_{DD}	Power supply		
B2	TEST	Open or short to GND		

OProduct structure: Silicon monolithic integrated circuit OThis product has no designed protection against radioactive rays

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Absolute Maximum Ratings (Ta = 25°C)

Parameter	Symbol	Rating	Unit
Power Supply Voltage	V_{DD}	-0.1 to +4.5 ^(Note 1)	V
Output Current	I _{OUT}	±0.5	mA
Power Dissipation	Pd	0.10 ^(Note 2)	W
Operating Temperature Range	T _{opr}	-40 to +85	°C
Storage Temperature Range	T _{stg}	-40 to +125	°C

⁽Note 1) Not to exceed Pd

(Note 2) Mounted on 24mm x 20mm x 1.6mm glass epoxy board. Reduce 1.00mW per 1°C above 25°C Caution: Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins and the internal circuitry. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

Recommended Operating Conditions (Ta= -40°C to +85°C)

Parameter	Symbol	Min	Тур	Max	Unit
Power Supply Voltage	V_{DD}	1.65	1.80	3.60	V

Magnetic, Electrical Characteristics (Unless otherwise specified V_{DD}=1.80V Ta=25°C)

metic, Liectrical Characteristics (Offices otherwise specified VDD-1.00V 1a-25 C)						
Parameter	Symbol	Min	Тур	Max	Unit	Conditions
Operate Point	B_{opN}	-47.5	-43.3	-	mT	Output: OUT (React to the north pole)
Release Point	B _{rpN}		-41.7	-37.5	mT	Output: OUT (React to the north pole)
Hysteresis	B_{hysN}	-	1.6	-	mT	
Period	Тр	-	50	100	ms	
Output High Voltage	Vон	V _{DD} -0.2	-	-	V	B _{rpN} <b <sup="">(Note 3) I_{OUT}=-0.5mA
Output Low Voltage	V _{OL}	-	-	0.2	V	B <b<sub>opN (Note 3) I_{OUT}=+0.5mA</b<sub>
Supply Current	$I_{DD(AVG)}$	-	3.5	5.5	μA	Average
Supply Current During Startup Time	$I_{\text{DD(EN)}}$	-	2.8	-	mA	During startup time value
Supply Current During Standby Time	I _{DD(DIS)}	-	1.8	-	μΑ	During standby time value

⁽Note 3) B = Magnetic Flux Density

¹mT=10Gauss

Positive ("+") polarity flux is defined as the magnetic flux from south pole which is direct toward to the branded face of the sensor.

After applying power supply, it takes one cycle of period (T_P) to become definite output.

Measurement Circuit

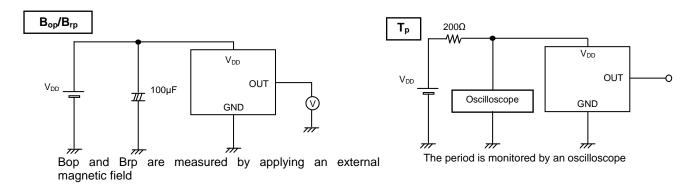


Figure 1. Bop, Brp Measurement Circuit

Figure 2. T_p Measurement Circuit

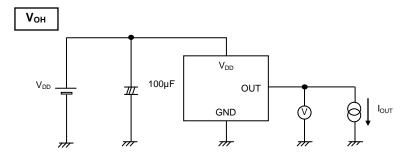


Figure 3. V_{OH} Measurement Circuit

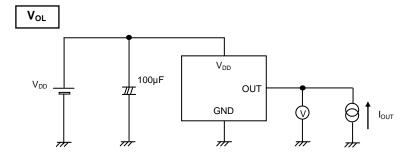


Figure 4. Vol Measurement Circuit

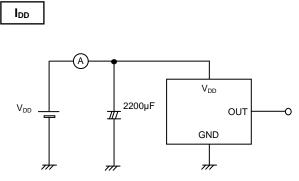


Figure 5. I_{DD} Measurement Circuit

Typical Performance Curves

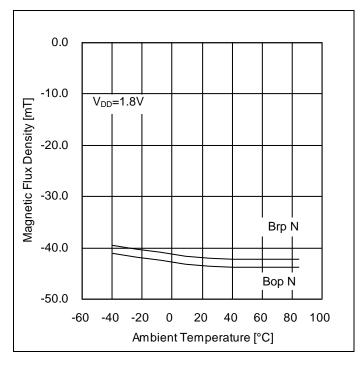


Figure 6. Operate Point, Release Point vs Ambient Temperature

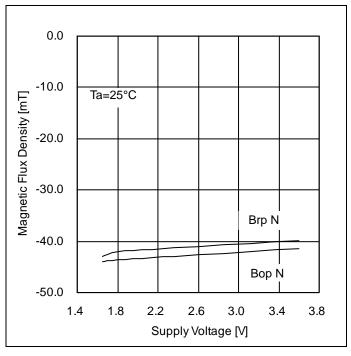


Figure 7. Operate Point, Release Point vs Supply Voltage

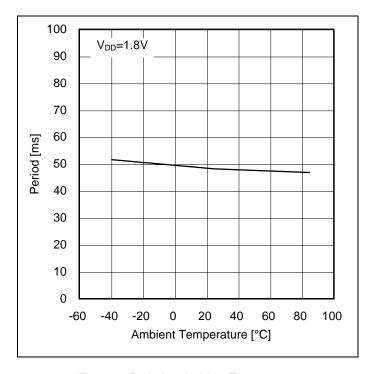


Figure 8. Period vs Ambient Temperature

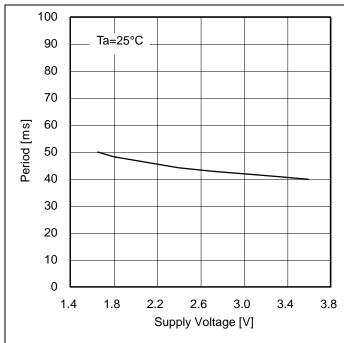
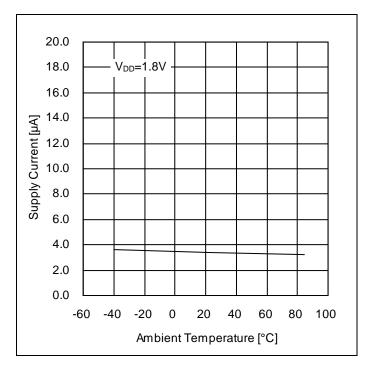


Figure 9. Period vs Supply Voltage

Typical Performance Curves - continued



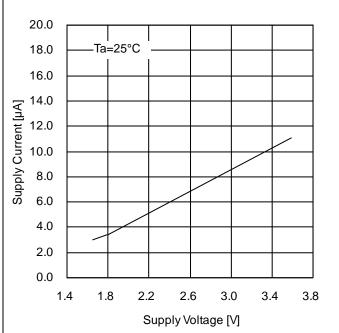


Figure 10. Supply Current vs Ambient Temperature

Figure 11. Supply Current vs Supply Voltage

Description of Operations

Micropower Operation (Small Current Consumption Using Intermittent Sensing)

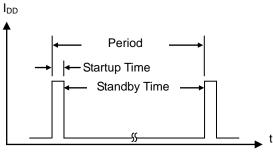


Figure 12

The unipolar detection Hall IC uses intermittent sensing save energy. At startup the Hall elements, amplifier, comparator, and other detection circuits power on and magnetic detection begins. During standby, the detection circuits power off, thereby reducing current consumption. The detection results are held while standby is active, and then output.

Reference Period: 50ms (MAX100ms) Reference Startup Time:24µs

(Offset Cancellation)

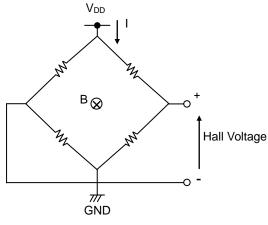


Figure 13

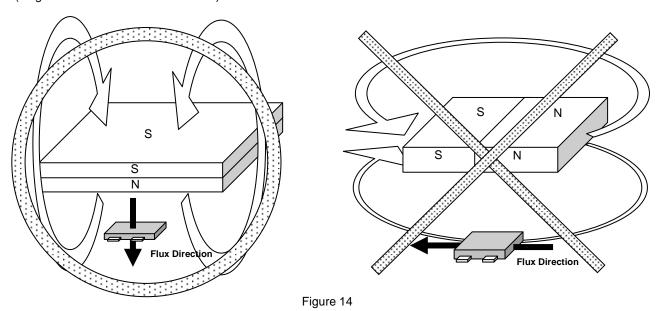
The Hall elements form an equivalent Wheatstone (resistor) bridge circuit. Offset voltage may be generated by a differential in this bridge resistance, or can arise from changes in resistance due to package or bonding stress. A dynamic offset cancellation circuit is employed to cancel this offset voltage.

When the Hall elements are connected as shown in Figure 13 and a magnetic field is applied perpendicular to the Hall elements, a voltage is generated at the mid-point terminal of the bridge. This is known as Hall voltage.

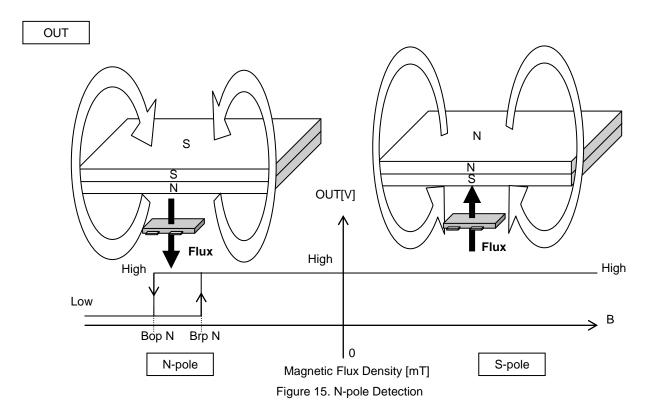
Dynamic cancellation switches the wiring (shown in the figure) to redirect the current flow to a 90° angle from its original path, and thereby cancels the Hall voltage.

The magnetic signal (only) is maintained in the sample/hold circuit during the offset cancellation process and then released.

(Magnetic Field Detection Mechanism)

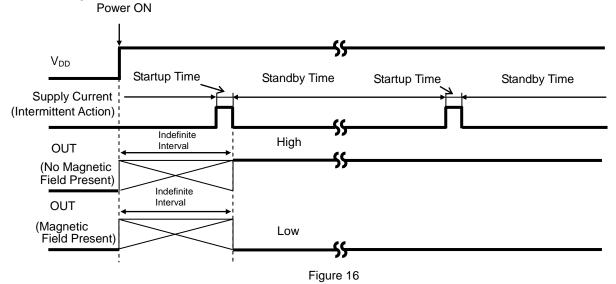


The Hall IC cannot detect magnetic fields that run horizontal to the package top layer. Be certain to configure the Hall IC so that the magnetic field is perpendicular to the top layer.



The OUT pin detects and outputs for the N-pole only. Since the OUT pin output is unipolar, the output does not respond to the S-pole. The unipolar detection Hall IC detects magnetic fields running perpendicular to the top surface of the package. There is an inverse relationship between magnetic flux density and the distance separating the magnet and the Hall IC: when distance increases magnetic density falls. When it drops below the operate point (Bop), output goes HIGH. When the magnet gets closer to the IC and magnetic density rises to the operate point, the output switches LOW. In LOW output mode, the distance from the magnet to the IC increases again until the magnetic density falls to a point just below Bop, and output returns HIGH. The point where magnetic flux density restores a HIGH output is known as the release point, Brp. This detection and adjustment mechanism is designed to prevent noise, oscillation, and other erratic system operation.

Intermittent Operation at Power ON



The unipolar detection Hall IC adopts an intermittent operation method in detecting the magnetic field during startup, as shown in Figure16. The IC outputs to the appropriate terminal based on the detection result and maintains the output condition during the standby period. The time from power ON until the end of the initial startup period is an indefinite interval, but it cannot exceed the maximum period of 100ms. To accommodate the system design, the Hall IC output read should be programmed within 100ms of power ON, but after the time allowed for the period, ambient temperature, and supply voltage.

Magnet Selection

Of the two representative varieties of permanent magnet, neodymium generally offers greater magnetic power per volume than ferrite, thereby enabling the highest degree of miniaturization, thus, neodymium is best suited for small equipment applications. Figure 17 shows the relation between the size (volume) of a neodymium magnet and magnetic flux density. The graph plots the correlation between the distance (L) from three versions of a 4mm x 4mm cross-section neodymium magnet (1mm, 2mm, and 3mm thick) and magnetic flux density. Figure 18 shows Hall IC detection distance – a good guide for determining the proper size and detection distance of the magnet. Based on the BU52069GWZ operating point min of -47.5mT, the minimum detection distance for the 1mm, 2mm and 3mm magnets would be 2.6mm, 3.4mm, and 4.0mm, respectively. To increase the magnet's detection distance, either increases the magnet's thickness or sectional area.

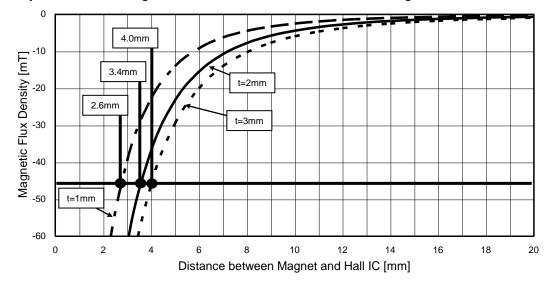


Figure 17. Magnetic Flux Density vs Distance between Magnet and Hall IC

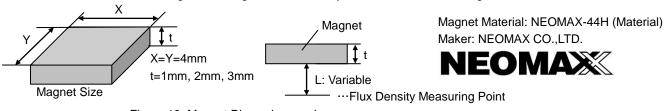


Figure 18. Magnet Dimensions and Flux Density Measuring Point

Slide-by Position Sensing

Figure 19 depicts the slide-by configuration employed for position sensing. Note that when the gap (d) between the magnet and the Hall IC is narrowed, the reverse magnetic field generated by the magnet can cause the IC to malfunction. As seen in Figure 20, the magnetic field runs in opposite directions at Point A and Point B. Since the unipolar detection Hall IC can detect the S-pole at Point A and the N-pole at Point B, the sensor can switch the output ON as the magnet slides by in the process of position detection. Figure 21 plots magnetic flux density during the magnet slide-by. Although a reverse magnetic field was generated in the process, the magnetic flux density decreases compared with the center of the magnet. This demonstrates that slightly widening the gap (d) between the magnet and Hall IC reduces the reverse magnetic field and prevents malfunctions.

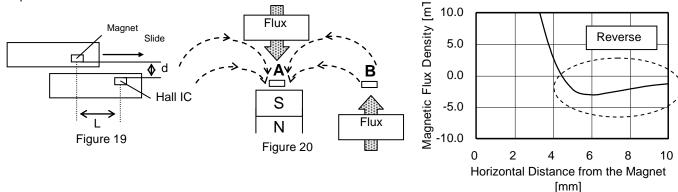
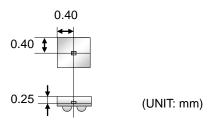


Figure 21. Magnetic Flux Density vs Horizontal Distance from the Magnet

Position of the Hall Element

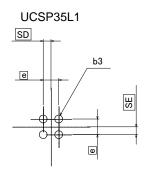
(Reference)

UCSP35L1



Footprint Dimensions

(Optimize footprint dimensions to the board design and soldering condition)



Symbol	Reference		
Syllibol	value		
е	0.40		
b3	φ0.20		
SD	0.20		
SE	0.20		

(UNIT: mm)

I/O Equivalence Circuit

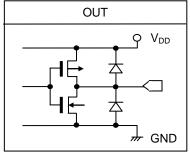


Figure 22

The Hall ICs output pins are configured for CMOS (inverter) output removing the need for external resistance and allow direct connection to the host. Removing the need for external resistors allows for reduction of the current that would otherwise flow to the external resistor during magnetic field detection thereby supporting an overall lower current (micropower) operation.

Operational Notes

1. Reverse Connection of Power Supply

Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply pins.

2. Power Supply Lines

Design the PCB layout pattern to provide low impedance supply lines. Separate the ground and supply lines of the digital and analog blocks to prevent noise in the ground and supply lines of the digital block from affecting the analog block. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

3. Ground Voltage

Ensure that no pins are at a voltage below that of the ground pin at any time, even during transient condition.

4. Ground Wiring Pattern

When using both small-signal and large-current ground traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the ground traces of external components do not cause variations on the ground voltage. The ground lines must be as short and thick as possible to reduce line impedance.

5. Thermal Consideration

Should by any chance the power dissipation rating be exceeded the rise in temperature of the chip may result in deterioration of the properties of the chip. In case of exceeding this absolute maximum rating, increase the board size and copper area to prevent exceeding the Pd rating.

6. Recommended Operating Conditions

These conditions represent a range within which the expected characteristics of the IC can be approximately obtained. The electrical characteristics are guaranteed under the conditions of each parameter.

7. Inrush Current

When power is first supplied to the IC, it is possible that the internal logic may be unstable and inrush current may flow instantaneously due to the internal powering sequence and delays, especially if the IC has more than one power supply. Therefore, give special consideration to power coupling capacitance, power wiring, width of ground wiring, and routing of connections.

8. Operation Under Strong Electromagnetic Field

Operating the IC in the presence of a strong electromagnetic field may cause the IC to malfunction.

9. Testing on Application Boards

When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

10. Inter-pin Short and Mounting Errors

Ensure that the direction and position are correct when mounting the IC on the PCB. Incorrect mounting may result in damaging the IC. Avoid nearby pins being shorted to each other especially to ground, power supply and output pin. Inter-pin shorts could be due to many reasons such as metal particles, water droplets (in very humid environment) and unintentional solder bridge deposited in between pins during assembly to name a few.

Operational Notes - continued

11. Unused Input Pins

Input pins of an IC are often connected to the gate of a MOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of the IC. So unless otherwise specified, unused input pins should be connected to the power supply or ground line.

12. Regarding the Input Pin of the IC

In the construction of this IC, P-N junctions are inevitably formed creating parasitic diodes or transistors. The operation of these parasitic elements can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions which cause these parasitic elements to operate, such as applying a voltage to an input pin lower than the ground voltage should be avoided. Furthermore, do not apply a voltage to the input pins when no power supply voltage is applied to the IC. Even if the power supply voltage is applied, make sure that the input pins have voltages within the values specified in the electrical characteristics of this IC.

13. Ceramic Capacitor

When using a ceramic capacitor, determine the dielectric constant considering the change of capacitance with temperature and the decrease in nominal capacitance due to DC bias and others.

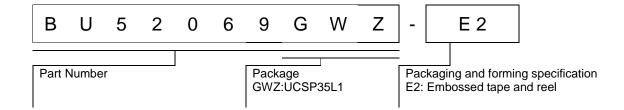
14. Area of Safe Operation (ASO)

Operate the IC such that the output voltage, output current, and power dissipation are all within the Area of Safe Operation (ASO).

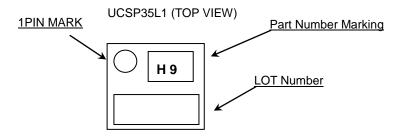
15. Disturbance light

In a device where a portion of silicon is exposed to light such as in a WL-CSP, IC characteristics may be affected due to photoelectric effect. For this reason, it is recommended to come up with countermeasures that will prevent the chip from being exposed to light.

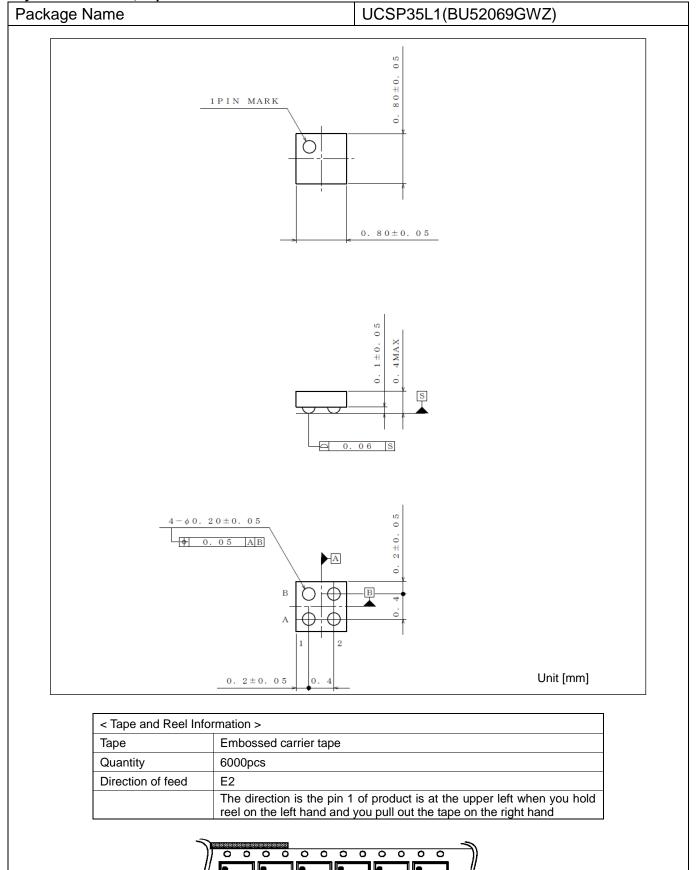
Ordering Information



Marking Diagrams



Physical Dimension, Tape and Reel Information



Mark PIN1

Reel

Direction of feed

Revision History

Date	Revision	Changes
7.Nov.2014	001	New Release

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CLASSIV	CLASSⅢ	CLASSⅢ	CLASSⅢ

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 - [f] Sealing or coating our Products with resin or other coating materials
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 may be degraded. It is strongly recommended to confirm solderability before using Products of which storage time is
 exceeding the recommended storage time period.
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- 4. Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

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